

## Solution

### DETERMINANTS WS 1

#### Class 12 - Mathematics

1.

(c) Idempotent

**Explanation:** clearly for given matrix  $A^2 = A$

Therefore idempotent

2.

(d) if  $\det. A = 0$ ,  $(\text{adj } A) B = O$

**Explanation:** If  $\det. A = 0$ ,  $(\text{adj } A) B = O \Rightarrow$  The system  $AX = B$  of  $n$  equations in  $n$  unknowns may be consistent with infinitely many solutions or it may be inconsistent.

3.

(c)  $\frac{15}{2}$

**Explanation:**  $\Delta = \begin{vmatrix} \log_3 512 & \log_4 3 \\ \log_3 8 & \log_4 9 \end{vmatrix} = \begin{vmatrix} \log_3 2^9 & \log_4 3^2 \\ \log_3 2^3 & \log_4 3^2 \end{vmatrix}$

$$= \begin{vmatrix} 9 \log_3 2 & \log_4 3 \\ 3 \log_3 2 & 2 \log_4 3 \end{vmatrix} = 18 \log_3 2 \times \log_4 3 - 3 \log_3 2 \times \log_4 3$$

$$= \log_3 2 \times \log_4 3 (18 - 3) = \frac{\ln 2}{\ln 3} \times \frac{\ln 3}{\ln 4} \times 15 \quad \left[ \because \log_a b = \frac{\ln b}{\ln a} \right]$$

$$= \frac{\ln 2}{\ln 4} \times 15 = \frac{\ln 2}{\ln 2^2} \times 15 = \frac{15 \ln 2}{2 \ln 2} = \frac{15}{2}$$

4.

(b)  $\text{adj } A$

**Explanation:**  $\text{adj } A$

5.

(d) 0

**Explanation:** 0

6.

(d)  $\pm 6$

**Explanation:** We have  $\begin{vmatrix} x & 2 \\ 18 & x \end{vmatrix} = \begin{vmatrix} 6 & 2 \\ 18 & 6 \end{vmatrix}$

We know that determinant of  $A$  is calculated as  $|A| = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$

$$\Rightarrow x(x) - 2(18) = 6(6) - 2(18)$$

$$\Rightarrow x^2 - 36 = 36 - 36$$

$$\Rightarrow x^2 = 36 - 36 + 36$$

$$\Rightarrow x^2 = 36$$

$$\Rightarrow x = \pm 6.$$

7.

(d)  $\frac{10}{7}$

**Explanation:** Let  $A(2, -3)$ ,  $B(\lambda, -1)$  and  $C(0, 4)$  are given points.

Given points are collinear

$$\therefore \text{ar}(\triangle ABC) = 0$$

$$\Rightarrow \frac{1}{2} \begin{vmatrix} 2 & -3 & 1 \\ \lambda & -1 & 1 \\ 0 & 4 & 1 \end{vmatrix} = 0 \Rightarrow |2(-1-4) - \lambda(-3-4) + 0| = 0$$

$$\Rightarrow |-10 + 7\lambda| = 0 \Rightarrow 7\lambda - 10 = 0 \Rightarrow \lambda = \frac{10}{7}$$

8. (a)  $BA^{-1}$

**Explanation:**  $(AB^{-1})^{-1} = (B^{-1})^{-1} A^{-1} = BA^{-1}$

9. (a)  $\frac{1}{2}$

**Explanation:**  $\Delta = \begin{vmatrix} 0 & \cos \theta & \sin \theta \\ \cos \theta & \sin \theta & 0 \\ \sin \theta & 0 & \cos \theta \end{vmatrix}^2$

$$= (-\cos \theta (\cos^2 \theta - \theta) + \sin \theta (0 - \sin^2 \theta))^2$$

$$= (-\cos^3 \theta - \sin^3 \theta)^2 = (\cos^3 \theta + \sin^3 \theta)^2$$

$$\text{Now } \cos 2\theta = 0 \Rightarrow 2\theta = (2n + 1)\frac{\pi}{2} \Rightarrow \theta = (2n + 1)\frac{\pi}{4}$$

$$\therefore \Delta = \left( \cos^3 \frac{(2n+1)\pi}{4} + \sin^3 \frac{(2n+1)\pi}{4} \right)^2$$

$$= \left( \frac{1}{2\sqrt{2}} + \frac{1}{2\sqrt{2}} \right)^2 = \left( \frac{1}{\sqrt{2}} \right)^2 = \frac{1}{2}$$

10. (a) 12

**Explanation:** 12

Explanation:

$$A \cdot (\text{adj } A) = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

we know that  $A \cdot (\text{Adj}A) = I \cdot |A|$

$$\Rightarrow \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix} = |A| I$$

$$\Rightarrow 3 \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = |A| I$$

$$\Rightarrow 3I = |A| I$$

$$\Rightarrow |A| = 3 \text{ ---(1)}$$

$$|\text{Adj } A| = |A|^{3-1} \text{ [ Since order } n=3]$$

$$|\text{Adj } A| = (3)^2 = 9$$

$$|\text{adj}(A)| = 9 \text{ -----(2)}$$

Now,

$$|A| + |\text{adj } A| = 3 + 9 = 12$$

11. (a)  $x = -\frac{6}{11}, y = -\frac{19}{11}$

**Explanation:** The given system can be written as  $AX = B$  where

$$A = \begin{bmatrix} 4 & -3 \\ 3 & -5 \end{bmatrix}, X = \begin{bmatrix} x \\ y \end{bmatrix}, B = \begin{bmatrix} 3 \\ 7 \end{bmatrix}$$

$$\text{Here, } |A| = \begin{vmatrix} 4 & -3 \\ 3 & -5 \end{vmatrix} = 4(-5) - 3(-3)$$

$$= -20 + 9 = -11 \neq 0$$

Thus, A is non-singular. Therefore, its inverse exists.

Therefore, the given system has a unique solution given by  $X = A^{-1} B$ .

$$\therefore \text{adj } (A) = \begin{bmatrix} -5 & 3 \\ -3 & 4 \end{bmatrix}$$

$$\therefore A^{-1} = \frac{1}{|A|} (\text{adj } A) = \frac{1}{-11} \begin{bmatrix} -5 & 3 \\ -3 & 4 \end{bmatrix}$$

$$\text{Now, } X = A^{-1} B = \frac{1}{-11} \begin{bmatrix} -5 & 3 \\ -3 & 4 \end{bmatrix} \begin{bmatrix} 3 \\ 7 \end{bmatrix}$$

$$= \frac{1}{-11} \begin{bmatrix} -15 + 21 \\ -9 + 28 \end{bmatrix}$$

$$= \frac{1}{-11} \begin{bmatrix} 6 \\ 19 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -\frac{6}{11} \\ -\frac{19}{11} \end{bmatrix}$$

$$\therefore x = -\frac{6}{11}, \text{ and } y = -\frac{19}{11}$$

12.

(d) Null matrix

**Explanation:** As we know that,  $A(\text{adj } A) = |A| I$ .

But it is given that A is a singular matrix

Thus,  $|A| = 0$ .

Therefore,  $A(\text{adj } A) = 0I = 0$ , where 0 is the zero matrix.

Hence, if A is a singular matrix, then  $A(\text{adj } A) = \underline{0}$ .

13.

(b)  $(A + B)^{-1} = B^{-1} + A^{-1}$

**Explanation:** Since, A and B are invertible matrices.

So, we can say that

$$(AB)^{-1} = B^{-1} A^{-1} \dots(i)$$

$$\text{We know that, } A^{-1} = \frac{1}{|A|} (\text{adj } A)$$

$$\Rightarrow \text{adj } A = |A| \cdot A^{-1} \dots(ii)$$

$$\text{Also, } \det(A)^{-1} = [\det(A)]^{-1}$$

$$\Rightarrow \det(A)^{-1} = \frac{1}{[\det(A)]}$$

$$\Rightarrow \det(A) \cdot \det(A)^{-1} = 1 \dots(iii)$$

Which is true,

So, only option d is incorrect.

14.

(c) AB is non-singular

**Explanation:** If A and B are non - singular then  $|AB| \neq 0$

= AB is non - singular matrix,

As  $|AB| = |A||B|$

15.

(b)  $\frac{61}{2}$  sq. units

**Explanation:** The area of triangle is given by

$$\Delta = \frac{1}{2} \begin{vmatrix} 3 & 8 & 1 \\ -4 & 2 & 1 \\ 5 & 1 & 1 \end{vmatrix}$$

$$= \frac{1}{2} [3(2 - 1) - 8(-4 - 5) + 1(-4 - 10)]$$

$$= \frac{1}{2} (3 + 72 - 14) = \frac{61}{2} \text{ sq. units}$$

16.

(b)  $a^6$

$$\text{Explanation: } A = \begin{bmatrix} a & 0 & 0 \\ 0 & a & 0 \\ 0 & 0 & a \end{bmatrix}$$

$$|A| = a^3$$

$$|\text{adj } A| = |A|^{3-1} = |A|^2$$

$$|\text{adj } A| = (a^3)^2 = a^6$$

17. (a)  $C^{-1}BA^{-1}$

**Explanation:** We know that  $(AB)^{-1} = B^{-1} A^{-1}$

$$\text{Hence, } (AB^{-1}C)^{-1} = C^{-1}(AB^{-1})^{-1} = C^{-1}(B^{-1})^{-1}A^{-1} = C^{-1}BA^{-1}$$

18.

(d)  $\mu$  only

**Explanation:** The given system of linear equation :-

$$x + y + z = \lambda$$

$$5x - y + \mu z = 10$$

$$2x + 3y - z = 6$$

The matrix equation corresponding to the above system is :

$$\begin{bmatrix} 1 & 1 & 1 \\ 5 & -1 & \mu \\ 2 & 3 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} \lambda \\ 10 \\ 6 \end{bmatrix}$$

$$\text{Suppose } A = \begin{bmatrix} 1 & 1 & 1 \\ 5 & -1 & \mu \\ 2 & 3 & -1 \end{bmatrix}$$

$$\therefore |A| = \begin{vmatrix} 1 & 1 & 1 \\ 5 & -1 & \mu \\ 2 & 3 & -1 \end{vmatrix} = 1(1-3\mu) - 1(-5-2\mu) + 1(15+2)$$

$$= 1 - 3\mu + 5 + 2\mu + 17 = 23 - \mu$$

For the existence of the unique solution, the value of  $|A|$  must not be equal to 0.

Therefore, the existence of the unique solution merely depends on the value of  $\mu$ . Which is the required solution.

19.

(c) None of these

**Explanation:** We have,

$$A = \begin{bmatrix} 2 & \lambda & -3 \\ 0 & 2 & 5 \\ 1 & 1 & 3 \end{bmatrix}$$

$A^{-1}$  exists if  $|A| \neq 0$

$$\text{Now } |A| = 2(6-5) - \lambda(-5) - 3(-2) = 8 + 5\lambda \neq 0$$

$$\Rightarrow 5\lambda \neq -8$$

$$\Rightarrow \lambda \neq \frac{-8}{5}$$

So,  $A^{-1}$  exists if and only if  $\neq \frac{-8}{5}$

20.

$$(b) \begin{bmatrix} 1 & 2 \\ \frac{1}{2} & \frac{3}{2} \end{bmatrix}$$

**Explanation:**  $B = I$

$$B = A^{-1} I \dots (i)$$

$$A^{-1} = \frac{1}{|A|} \text{adj } A \dots (ii)$$

$$|A| = 3 \times 2 - (-4) \times (-1)$$

$$= 2$$

$$C_{11} = 2, C_{12} = 1$$

$$C_{21} = 4, C_{22} = 3$$

$$\text{Co-factor matrix } A = \begin{pmatrix} 2 & 1 \\ 4 & 3 \end{pmatrix}$$

$$\text{Adj } A = \begin{pmatrix} 2 & 1 \\ 4 & 3 \end{pmatrix}'$$

$$= \begin{pmatrix} 2 & 4 \\ 1 & 3 \end{pmatrix}$$

Putting in 2

$$A^{-1} = \frac{1}{|2|} \begin{pmatrix} 2 & 4 \\ 1 & 3 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 2 \\ \frac{1}{2} & \frac{3}{2} \end{pmatrix}$$

Put this value in equation (i)

$$B = A^{-1} I$$

$$= A^{-1}$$

$$= \begin{pmatrix} 1 & 2 \\ \frac{1}{2} & \frac{3}{2} \end{pmatrix}$$

21.

(c) 26

**Explanation:**  $f(x) = \begin{vmatrix} x & -4 & 5 \\ 1 & 1 & -2 \\ 2 & x & 1 \end{vmatrix} = x(1 + 2x) - 1(-4 - 5x) + 2(8 - 5)$

$$= x + 2x^2 + 4 + 5x + 6 = 2x^2 + 6x + 10$$

$$f'(x) = 4x + 6$$

$$f'(5) = 20 + 6 = 26$$

22. (a) no solution

**Explanation:** The given system of equations does not have solution if :  $\begin{vmatrix} 1 & 4 & -2 \\ 3 & 1 & 5 \\ 2 & 3 & 1 \end{vmatrix} = 0 \Rightarrow 1(-14) - 4(-7) - 2(7) = 0$

23.

(b) -52

**Explanation:** For easier calculations, we shall expand the determinant along that row or column which contains maximum number of zeroes.

Note that in the third column, two entries are zero.

24. (a)  $\Delta \in [2, 4]$

**Explanation:**  $\Delta = \begin{vmatrix} 1 & \sin \theta & 1 \\ -\sin \theta & 1 & \sin \theta \\ -1 & -\sin \theta & 1 \end{vmatrix}$

$$= 1(1 + \sin^2 \theta) - \sin \theta(-\sin \theta + \sin \theta) + 1(\sin 2\theta + 1)$$

$$\Delta = 2(1 + \sin^2 \theta) \dots (i)$$

$$\text{Now, } -1 \leq \sin^2 \theta \leq 1$$

$$\Rightarrow 0 + 1 \leq 1 + \sin^2 \theta \leq 1 + 1$$

$$\Rightarrow 1 \leq 1 + \sin^2 \theta \leq 2$$

$$\Rightarrow 2 \leq 2(1 + \sin^2 \theta) \leq 4$$

$$\Rightarrow 2 \leq \Delta \leq 4 \text{ [From (i)]}$$

$$\Rightarrow \Delta \in [2, 4]$$

25.

(b)  $a = \cos 2\theta$ ,  $b = \sin 2\theta$

**Explanation:**  $\begin{bmatrix} 1 & -\tan \theta \\ \tan \theta & 1 \end{bmatrix} \begin{bmatrix} 1 & \tan \theta \\ -\tan \theta & 1 \end{bmatrix}^{-1} = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$

$$\begin{bmatrix} 1 & -\tan \theta \\ \tan \theta & 1 \end{bmatrix} \frac{1}{\sec^2 \theta} \begin{bmatrix} 1 & -\tan \theta \\ \tan \theta & 1 \end{bmatrix} = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$$

$$\frac{1}{\sec^2 \theta} \begin{bmatrix} 1 & -\tan \theta \\ \tan \theta & 1 \end{bmatrix} \begin{bmatrix} 1 & -\tan \theta \\ \tan \theta & 1 \end{bmatrix} = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$$

$$\begin{bmatrix} \frac{1 - \tan^2 \theta}{\sec^2 \theta} & \frac{-2 \tan \theta}{\sec^2 \theta} \\ \frac{2 \tan \theta}{\sec^2 \theta} & \frac{1 - \tan^2 \theta}{\sec^2 \theta} \end{bmatrix} = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$$

$$a = \frac{1 - \tan^2 \theta}{\sec^2 \theta} \text{ Use tan in terms of sin and cos and simplify, we get,}$$

$$a = \cos^2 \theta - \sin^2 \theta$$

$$a = \cos 2\theta$$

$$\text{and } b = \frac{2 \tan \theta}{\sec^2 \theta} = \sin 2\theta$$

26. (a) Singular

**Explanation:**  $\begin{vmatrix} ab & b^2 \\ -a^2 & -ab \end{vmatrix} = -a^2 b^2 + a^2 b^2 = 0$

Therefore, it is Singular.

27.

$$(c) \begin{vmatrix} 10 & 0 & 0 \\ 0 & 10 & 0 \\ 0 & 0 & 10 \end{vmatrix}$$

$$\text{Explanation: } \begin{vmatrix} 10 & 0 & 0 \\ 0 & 10 & 0 \\ 0 & 0 & 10 \end{vmatrix}$$

28.

(d)  $\pm 6$

$$\text{Explanation: We have } \begin{vmatrix} 2x & 5 \\ 8 & x \end{vmatrix} = \begin{vmatrix} 6 & -2 \\ 7 & 3 \end{vmatrix}$$

$$\Rightarrow 2x^2 - 40 = 18 + 14$$

$$\Rightarrow 2x^2 = 72$$

$$\Rightarrow x^2 = 36$$

$$\Rightarrow x = \pm 6$$

29.

$$(d) \frac{1}{13} \begin{vmatrix} 5 & -1 \\ -2 & 3 \end{vmatrix}$$

$$\text{Explanation: } A = \begin{vmatrix} 3 & 1 \\ 2 & 5 \end{vmatrix}, |A| = 15 - 2 = 13$$

$$\text{adj}(A) = \begin{vmatrix} 5 & -1 \\ -2 & 3 \end{vmatrix}$$

$$\therefore A^{-1} = \frac{1}{13} \begin{vmatrix} 5 & -1 \\ -2 & 3 \end{vmatrix}$$

30.

$$(b) \begin{vmatrix} 6 & 2 \\ 11/2 & 2 \end{vmatrix}$$

$$\text{Explanation: } \begin{vmatrix} 1 & -4 \\ 3 & -2 \end{vmatrix} X = \begin{vmatrix} -16 & -6 \\ 7 & 2 \end{vmatrix} \Rightarrow X = \begin{vmatrix} 1 & -4 \\ 3 & -2 \end{vmatrix}^{-1} \begin{vmatrix} -16 & -6 \\ 7 & 2 \end{vmatrix}$$

$$\Rightarrow X = \frac{1}{10} \begin{vmatrix} -2 & 4 \\ -3 & 1 \end{vmatrix} \begin{vmatrix} -16 & -6 \\ 7 & 2 \end{vmatrix} = \frac{1}{10} \begin{vmatrix} 60 & 20 \\ 55 & 20 \end{vmatrix} = \begin{vmatrix} 6 & 2 \\ 11/2 & 2 \end{vmatrix}$$

31.

(b) 4

$$\text{Explanation: } A = \begin{vmatrix} 1 & 2 \\ 4 & 2 \end{vmatrix}, 2A = \begin{vmatrix} 2 & 4 \\ 8 & 4 \end{vmatrix}$$

$$12A = 8 - 32 = -24$$

$$1A = 2 - 8 = -6$$

$$\therefore |2A| = 4 \times (-6) = 4|A|$$

$$\Rightarrow k = 4$$

32. (a) 1

$$\text{Explanation: We have, } \begin{vmatrix} x & x+1 \\ x-1 & x \end{vmatrix} = x(x) - (x+1)(x-1)$$

$$= x^2 - (x^2 - 1)$$

$$= x^2 - x^2 + 1 = 1$$

33.

(c)  $\frac{1}{3}$

$$\text{Explanation: We have, } A = \begin{bmatrix} 1 & 4 \\ 3 & 15 \end{bmatrix}$$

$$\text{Now, } |A| = \begin{vmatrix} 1 & 4 \\ 3 & 15 \end{vmatrix} = 15 - 12 = 3$$

$$\therefore |A^{-1}| = |A|^{-1} = (3)^{-1} = \frac{1}{3}$$

34. (a) do not lie in a straight line

**Explanation:** Given, the points are

$(a + 5, a - 4), (a - 2, a + 3)$  and  $(a, a),$

$$\therefore \Delta = \frac{1}{2} \begin{vmatrix} a+5 & a-4 & 1 \\ a-2 & a+3 & 1 \\ a & a & 1 \end{vmatrix}$$

Applying  $R_1 \rightarrow R_1 - R_3$  and  $R_2 \rightarrow R_2 - R_3,$

we get

$$= \frac{1}{2} \begin{vmatrix} 5 & -4 & 0 \\ -2 & 3 & 0 \\ a & a & 1 \end{vmatrix} = \frac{1}{2} [1(15 - 8)] = \frac{7}{2} \neq 0$$

Hence, given points form a triangle i.e. points do not lie in a straight line.

35.

(d) 3

**Explanation:** The given system of equations does not have solution if  $\begin{vmatrix} 1 & 1 & 1 \\ 4 & \lambda & -\lambda \\ 3 & 2 & -4 \end{vmatrix} = 0 \Rightarrow \begin{vmatrix} 0 & 0 & 1 \\ 4 + \lambda & 2\lambda & -\lambda \\ 7 & 6 & 4 \end{vmatrix} = 0$

$$\Rightarrow (24 + 6\lambda - 14\lambda) = 0 \Rightarrow \lambda = 3$$

36.

(b)  $x = \frac{11}{24}, y = \frac{1}{24}$

**Explanation:**  $x = \frac{11}{24}, y = \frac{1}{24}$

37.

(b)  $(A^T)^{-1}$

**Explanation:**  $(A^T)^{-1}$

38.

(b) 3

**Explanation:** We know that, area of a triangle with vertices  $(x_1, y_1), (x_2, y_2)$  and  $(x_3, y_3)$  is given by

$$\Delta = \frac{1}{2} \begin{vmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_3 & y_3 & 1 \end{vmatrix}$$

$\therefore$  Area of triangle with vertices  $(-3, 0), (3, 0)$  and  $(0, k)$  is given by:

$$\Delta = \frac{1}{2} \begin{vmatrix} -3 & 0 & 1 \\ 3 & 0 & 1 \\ 0 & k & 1 \end{vmatrix}$$

$$\Rightarrow [-3(-k) - 0 + 1(3k)] = \pm 18$$

$$\Rightarrow 6k = \pm 18$$

$$\therefore k = \pm \frac{18}{6} = \pm 3$$

39.

(c) no solution

**Explanation:** The given system of equations does not has a solution if:  $\begin{vmatrix} 3 & 1 & -1 \\ 5 & 2 & -3 \\ 15 & 6 & -9 \end{vmatrix} = 0 \Rightarrow 3(-18 + 18) - 1(-45 + 45) - 1(30 - 30) = 0$

40.

(a) 1

**Explanation:** Given:  $A(\text{adj}(A)) = \begin{vmatrix} k & 0 \\ 0 & k \end{vmatrix} = k \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} = KI$

$$\Rightarrow k = 1$$

41.

(b) -6, 4

**Explanation:** -6, 4

42.

(c) -2

**Explanation:** -2

43.

(b)  $\begin{bmatrix} 4 & -2 \\ -3 & 1 \end{bmatrix}$

**Explanation:** Let  $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$  then  $|A| = \begin{vmatrix} 1 & 2 \\ 3 & 4 \end{vmatrix}$ .

Now, cofactors of elements of  $|A|$  are

$$C_{11} = (-1)^{1+1} 4 = 4,$$

$$C_{12} = (-1)^{1+2} (3) = -3,$$

$$C_{21} = (-1)^{2+1} (2) = -2$$

and  $C_{22} = (-1)^{2+2} (1) = 1$

Now,  $\text{adj}(A) = \begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix}^T$

$$= \begin{bmatrix} 4 & -3 \\ -2 & 1 \end{bmatrix}^T$$

$$= \begin{bmatrix} 4 & -2 \\ -3 & 1 \end{bmatrix}$$

44.

(d)  $\begin{vmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_3 & y_3 & 1 \end{vmatrix} = \pm 2A$

**Explanation:**  $\begin{vmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_3 & y_3 & 1 \end{vmatrix} = \pm 2A$

Explanation:

$$A = \frac{1}{2} [x_1 (y_2 - y_3) - x_2 (y_1 - y_3) + x_3 (y_1 - y_2)]$$

$$2A = [x_1 (y_2 - y_3) - x_2 (y_1 - y_3) + x_3 (y_1 - y_2)]$$

45.

(c)

$$|A|I$$

**Explanation:** Since, we know that

$$A^{-1} = \frac{\text{adj}A}{|A|}$$

pre multiply by A,

$$AA^{-1} = \frac{A \text{adj}A}{|A|}$$

$$I = \frac{A \text{adj}A}{|A|} \Rightarrow A \text{adj}A = |A| I \quad (\text{since } AA^{-1} = I)$$

46.

(c)  $A^2 + B^2$

**Explanation:**  $B = -A^{-1}BA$

$$\Rightarrow AB = -AA^{-1}BA$$

$$\Rightarrow AB = -IBA$$

$$\Rightarrow AB = -BA$$

$$\Rightarrow AB + BA = O \dots(i)$$

Consider,  $(A + B)^2 = A^2 + AB + BA + B^2 \dots(\because AB \neq BA)$

$$(A + B)^2 = A^2 + O + B^2 \dots \text{from (i)}$$

$$(A + B)^2 = A^2 + B^2$$

47.

$$(b) \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix}$$

$$\text{Explanation: } A = \begin{vmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{vmatrix}$$

$$\begin{aligned} A^T A &= \begin{vmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{vmatrix} \begin{vmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{vmatrix} \\ &= \begin{vmatrix} \cos^2 \alpha + \sin^2 \alpha & \cos \alpha \sin \alpha - \sin \alpha \cos \alpha \\ \sin \alpha \cos \alpha - \sin \alpha \cos \alpha & \sin^2 \alpha + \cos^2 \alpha \end{vmatrix} \\ &= \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} \end{aligned}$$

48.

(c) unique solution

**Explanation:** The given system of linear equations is:-

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1$$

$$\frac{x^2}{a^2} - \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$

$$-\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$

Let  $x^2 = p$ ,  $y^2 = q$ ,  $z^2 = r$

The equation becomes,

$$\frac{p}{a^2} + \frac{q}{b^2} - \frac{r}{c^2} = 1$$

$$\frac{p}{a^2} - \frac{q}{b^2} + \frac{r}{c^2} = 1$$

$$-\frac{p}{a^2} + \frac{q}{b^2} + \frac{r}{c^2} = 1$$

The matrix equation corresponding to the above system of equation is

$$\begin{bmatrix} \frac{1}{a^2} & \frac{1}{b^2} & -\frac{1}{c^2} \\ \frac{1}{a^2} & -\frac{1}{b^2} & \frac{1}{c^2} \\ -\frac{1}{a^2} & \frac{1}{b^2} & \frac{1}{c^2} \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 5 \\ 9 \\ \mu \end{bmatrix}$$

$$\text{Let } A = \begin{bmatrix} \frac{1}{a^2} & \frac{1}{b^2} & -\frac{1}{c^2} \\ \frac{1}{a^2} & -\frac{1}{b^2} & \frac{1}{c^2} \\ -\frac{1}{a^2} & \frac{1}{b^2} & \frac{1}{c^2} \end{bmatrix}$$

$$\therefore |A| = \begin{vmatrix} \frac{1}{a^2} & \frac{1}{b^2} & -\frac{1}{c^2} \\ \frac{1}{a^2} & -\frac{1}{b^2} & \frac{1}{c^2} \\ -\frac{1}{a^2} & \frac{1}{b^2} & \frac{1}{c^2} \end{vmatrix}$$

Taking common  $\frac{1}{a^2}$  from  $C_1$ ,  $\frac{1}{b^2}$  from  $C_2$  and  $\frac{1}{c^2}$  from  $C_3$  we get,

$$|A| = \frac{1}{a^2} \frac{1}{b^2} \frac{1}{c^2} \begin{vmatrix} 1 & 1 & -1 \\ 1 & -1 & 1 \\ -1 & 1 & 1 \end{vmatrix} = \frac{-4}{a^2 b^2 c^2} \neq 0.$$

49.

(d) non-singular matrix

**Explanation:** non-singular matrix

50.

(c)  $2^6$

**Explanation:**  $|A| = d$

$$|\text{adj } A| = |A|^{n-1}$$

Here,  $n = 3$ ,  $|A| = 8$

$$|\text{adj } A| = 8^2$$

$$|\text{adj } A| = (2^3)^2 = 2^6$$

51.

**(d)** infinitely many solution

**Explanation:** Given equations are:

$$3x - 5y = 7 \dots(i)$$

$$\text{and } 6x - 10y = 14 \text{ or } 3x - 5y = 7 \dots(ii)$$

Equations (i) and (ii) are same.

Hence it will have infinitely many solutions.

52.

**(c)** a unique solution

**Explanation:** a unique solution

The given system of equations can be written in matrix form as follows:

$$\begin{bmatrix} 1 & 1 & 1 \\ 3 & -1 & 2 \\ 3 & 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2 \\ 6 \\ -18 \end{bmatrix}$$

$$AX = B$$

Here,

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 3 & -1 & 2 \\ 3 & 1 & 1 \end{bmatrix}, X = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \text{ and } B = \begin{bmatrix} 2 \\ 6 \\ -18 \end{bmatrix}$$

$$|A| = 1(-1 - 2) - 1(-3 - 6) + 1(3 + 3)$$

$$= -3 + 3 + 6$$

$$= 6 \text{ not equal to } 0.$$

So, the given system of equations has a unique solution.

53.

**(b)** 27 |A|

**Explanation:** If A is a matrix of order  $3 \times 3$ , then

$$|3A| = 3 \times 3 \times 3 |A| = 27 |A|$$

54.

**(b)** adj A

$$\text{Explanation: } A = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

$$|A| = \cos^2 \theta - (-\sin^2 \theta)$$

$$= \cos^2 \theta + (\sin^2 \theta)$$

$$= 1 \dots(i)$$

$$\text{We know that } A^{-1} = \frac{1}{|A|} \text{adj } A$$

$$= \text{adj } A \text{ [From I]}$$

55.

**(c)**  $\pm 2$

**Explanation:** Since, the area of the  $\triangle ABD$  is 3 sq units, then we have

$$\frac{1}{2} \begin{vmatrix} 1 & 3 & 1 \\ 0 & 0 & 1 \\ k & 0 & 1 \end{vmatrix} = \pm 3$$

$$\Rightarrow \frac{1}{2} [0 + 0 - 1(0 - 3k)] = \pm 3$$

$$\Rightarrow \frac{3k}{2} = \pm 3$$

$$\Rightarrow k = \pm 2$$

56.

**(a)**  $\begin{bmatrix} \frac{3}{7} & \frac{1}{7} \\ \frac{-1}{7} & \frac{2}{7} \end{bmatrix}$

$$\text{Explanation: } A^{-1} = \frac{1}{|A|} \text{adj } A \dots(i)$$

$$|A| = 3 \times 2 - (1) \times (-1)$$

$$= 7$$

$$C_{11} = 3, C_{12} = -1$$

$$C_{21} = 1, C_{22} = 2$$

$$\text{Co-factor matrix } A = \begin{pmatrix} 2 & 1 \\ 4 & 3 \end{pmatrix}$$

$$\text{Adj } A = \begin{pmatrix} 3 & -1 \\ 1 & 2 \end{pmatrix}'$$

$$= \begin{pmatrix} 3 & 1 \\ -1 & 2 \end{pmatrix}$$

Putting in 1

$$A^{-1} = \frac{1}{|7|} \begin{pmatrix} 3 & 1 \\ -1 & 2 \end{pmatrix}$$

$$= \begin{pmatrix} \frac{3}{7} & \frac{1}{7} \\ -\frac{1}{7} & \frac{2}{7} \end{pmatrix}$$

57.

(b) Non-existent

**Explanation:**  $\begin{bmatrix} 5 & 10 & 3 \\ -2 & -4 & 6 \\ -1 & -2 & b \end{bmatrix}$  is singular matrix. So its determinant value of this matrix is zero.

$$\text{i.e., } \begin{vmatrix} 5 & 10 & 3 \\ -2 & -4 & 6 \\ -1 & -2 & b \end{vmatrix} = 0$$

$$\Rightarrow 5(-4b + 12) - 10(-2b + 6) + 3(4 - 4) = 0$$

$$\Rightarrow -20b + 60 + 20b - 60 = 0$$

b does not exist

58.

(c) all integral  $\alpha$

**Explanation:** The given system of equations has unique solution, if:

$$\begin{vmatrix} 1 & 1 & 1 \\ 3 & 6 & 1 \\ \alpha & 2 & 3 \end{vmatrix} \neq 0$$

$$\Rightarrow 1(18 - 2) - 1(9 - \alpha) + 1(6 - 6\alpha) \neq 0$$

$$\Rightarrow 13 - 5\alpha \neq 0$$

$$\Rightarrow \alpha \neq \frac{13}{5}. \text{ (Since } \alpha \text{ is not integral value)}$$

Thus, unique solution exists for all integral values of  $\alpha$ .

59.

(d)  $x = 1, y = 1$

$$\text{Explanation: } \begin{pmatrix} x & y \\ 3y & x \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$= \begin{pmatrix} x \times 1 + y \times 2 \\ 3y \times 1 + x \times 2 \end{pmatrix}$$

$$= \begin{pmatrix} x + 2y \\ 3y + 2x \end{pmatrix}$$

Comparing with R.H.S

$$x + 2y = 3 \dots \text{(i)}$$

$$2x + 3y = 5 \dots \text{(ii)}$$

$$\text{(i) } \times 2 - \text{(ii)}$$

$$2x + 4y - 2x + 3y = 6 - 5$$

$$y = 1$$

Putting y in (i)

$$x + 2(1) = 3$$

$$x = 1$$

60. (a)  $\begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$

**Explanation:**  $S = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$

$$M_{11} = d \Rightarrow A_{11} = d$$

$$M_{12} = c \Rightarrow A_{12} = -c$$

$$M_{21} = b \Rightarrow A_{21} = -b$$

$$M_{22} = a \Rightarrow A_{22} = a$$

$$\Rightarrow \text{Ad}(A) = \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

61.

$$(c) \begin{vmatrix} 4/11 & 1/11 \\ -3/11 & 2/11 \end{vmatrix}$$

$$\text{Explanation: } A = \begin{vmatrix} 2 & -1 \\ 3 & 4 \end{vmatrix}, \text{adj } A = \begin{vmatrix} 4 & 1 \\ -3 & 2 \end{vmatrix}$$

$$|A| = 8 + 3 = 11$$

$$\therefore A^{-1} = \frac{1}{|A|}(\text{adj } A) = \frac{1}{11} \begin{vmatrix} 4 & 1 \\ -3 & 2 \end{vmatrix} = \begin{vmatrix} 4/11 & 1/11 \\ -3/11 & 2/11 \end{vmatrix}$$

62.

(c) 0

**Explanation:** Determinant value of skew-symmetric matrix is always '0'.

63.

(c)  $PX = -X$

**Explanation:** Given  $P' = 2P + I$

$$\Rightarrow (P')' = (2P + I)' = 2P' + I' = 2P' + I$$

$$\Rightarrow P = 2(2P + I) + I = 4P + 2I + I$$

$$\Rightarrow P = 4P + 3I \Rightarrow -3P = 3I \Rightarrow P = -I$$

$$\therefore PX = -IX = -X$$

64.

(c) One solution

**Explanation:** For Unique solution,  $\frac{a_1}{a_2} \neq \frac{b_1}{b_2}$ ,

for given system of equations we have:  $\frac{2}{1} \neq \frac{1}{-2}, \frac{1}{3} \neq \frac{-2}{5}, \frac{3}{2} \neq \frac{5}{1}$

65.

(d) 0 or 1

**Explanation:** Since,  $A^2 = A \Rightarrow |A|^2 = |A|$

$\therefore (\text{Det. } A)(\text{Det. } A) = \text{Det. } A, \therefore \text{det. } A [ \text{det. } A - 1 ] = 0. \therefore \text{det. } A = 0 \text{ or } 1.$

66.

(d)  $k \neq 0$

**Explanation:** In the given question the system of linear equation has unique solution if:

$$\begin{vmatrix} 1 & 1 & 1 \\ 2 & 1 & -1 \\ 3 & 2 & -k \end{vmatrix} \neq 0 \Rightarrow 1(-k + 2) - 1(-2k + 3) + 1(4 - 3) \neq 0 \Rightarrow k \neq 0$$

67.

(c)  $a_1b_2 = a_2b_1$

**Explanation:** Given that, the three points are collinear.

$$\therefore \frac{1}{2} \begin{vmatrix} a_1 & b_1 & 1 \\ a_2 & b_2 & 1 \\ a_1 + a_2 & b_1 + b_2 & 1 \end{vmatrix} = 0$$

$$\Rightarrow \begin{vmatrix} a_1 & b_1 & 1 \\ a_2 & b_2 & 1 \\ a_1 + a_2 & b_1 + b_2 & 1 \end{vmatrix} = 0$$

Applying  $R_2 \rightarrow R_2 - R_1$  and  $R_3 \rightarrow R_3 - R_1$ ,

we get

$$\begin{vmatrix} a_1 & b_1 & 1 \\ a_2 - a_1 & b_2 - b_1 & 0 \\ a_2 & b_2 & 0 \end{vmatrix} = 0$$

$$\Rightarrow \begin{vmatrix} a_2 - a_1 & b_2 - b_1 \\ a_2 & b_2 \end{vmatrix} = 0 \text{ [expanding along } C_3]$$

$$\Rightarrow b_2(a_2 - a_1) - a_2(b_2 - b_1) = 0$$

$$\Rightarrow a_2b_2 - a_1b_1 - a_2b_2 + a_2b_1 = 0$$

$$\therefore a_1b_2 = a_2b_1$$

68.

(d) independent of  $\theta$  only

**Explanation:** Let  $\Delta = \begin{vmatrix} x & \sin \theta & \cos \theta \\ -\sin \theta & -x & 1 \\ \cos \theta & 1 & x \end{vmatrix}$

By expanding along first row, we get

$$\Delta = x \begin{vmatrix} -x & 1 \\ 1 & x \end{vmatrix} - \sin \theta \begin{vmatrix} -\sin \theta & 1 \\ \cos \theta & x \end{vmatrix} + \cos \theta \begin{vmatrix} -\sin \theta & -x \\ \cos \theta & 1 \end{vmatrix}$$

$$= x(-x^2 - 1) - \sin \theta(-x \sin \theta - \cos \theta) + \cos \theta(-\sin \theta + x \cos \theta)$$

$$= -x^3 - x + x \sin^2 \theta + \sin \theta \cos \theta - \sin \theta \cos \theta + x \cos^2 \theta$$

$$= -x^3 - x + x(\sin^2 \theta + \cos^2 \theta) = -x^3 - x + x[ \sin^2 \theta + \cos^2 \theta = 1]$$

$$= -x^3$$

Hence,  $\Delta$  is independent of  $\theta$ .

69. (a) 14641

**Explanation:** We know that, for a square matrix of order n, if  $|A| \neq 0$

$$\text{Adj}(\text{Adj } A) = |A|^{n-2} A \quad (: n = 3)$$

$$\therefore \text{Adj}(\text{Adj } A) = |A|^{3-2} A \quad (: n = 3)$$

$$= |A| A$$

$$\therefore |\text{Adj}(\text{Adj } A)| = ||A| A| = |A|^3 \det A |A|^4$$

$$= 11^4 = 14641$$

70.

(b) singular

**Explanation:** Given,  $A = \begin{bmatrix} 1 & 2 \\ 6 & 12 \end{bmatrix}$

$$\text{Now, } |A| = \begin{vmatrix} 1 & 2 \\ 6 & 12 \end{vmatrix}$$

$$= 12 - 12 = 0$$

Hence, A is a singular matrix.

71.

(c) None of these

**Explanation:** If  $\det(A+B) = 0$  implies that A+B a Singular matrix.

72.

(d) (2, 4)

**Explanation:** (2, 4)

73.

(c)  $A^{-1} = |A|^{-1}$

**Explanation:**  $A^{-1} = |A|^{-1}$

74. (a) 16

**Explanation:** Since, A is a square matrix of order 3 i.e. n = 3

we know that

$$|\text{adj } A| = (A)^{n-1}$$

$$|\text{adj}(\text{adj } A)| = |A|^{(n-1)^2}$$

$$= 2^{(3-1)^2} \dots (\because |A| = 2)$$

$$= 2^4$$

$$= 16$$

75.

**(d)** 27

**Explanation:** We have,  $A^2 = 3A \Rightarrow |A^2| = |3A|$

$\Rightarrow |A| \cdot |A| = 3^3 |A|$  ( $\because$  order of matrix A is 3 and  $|A|$  is not equal to zero)

$\Rightarrow |A| = 3^3 = 27 \Rightarrow |A| = 27$